

7.8
Million EUFunding



12 partners



01 Jan 2024 -31 Dec 2027







Mondragon Faculty of Unibertsitatea Engineering







civitta











Funded by the European Union. Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or the European Health and Digital Executive Agency (HADEA). Neither the European Union nor HADEA can be held responsible for them, EU - HE Inverse - Grant Agreement 101136067



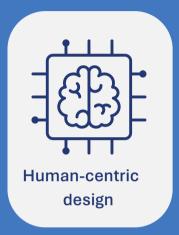
INteractive robots that intuitiVely lEarn to inVErt tasks by ReaSoning about their Execution

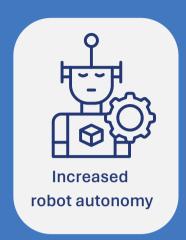
Advancing robotic technology through continous learning and adaptation





## **Expected impacts**













## **Our Vision**

We will develop robots that are able to:

- **understand** their surroundings, including human intentions and needs.
- **expand** and **improve** the robotic knowledge to perform flexible actions, such as reversing tasks.
- **continuously adapt** robotic knowledge to different domains.

