



Funded by
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INVERSE

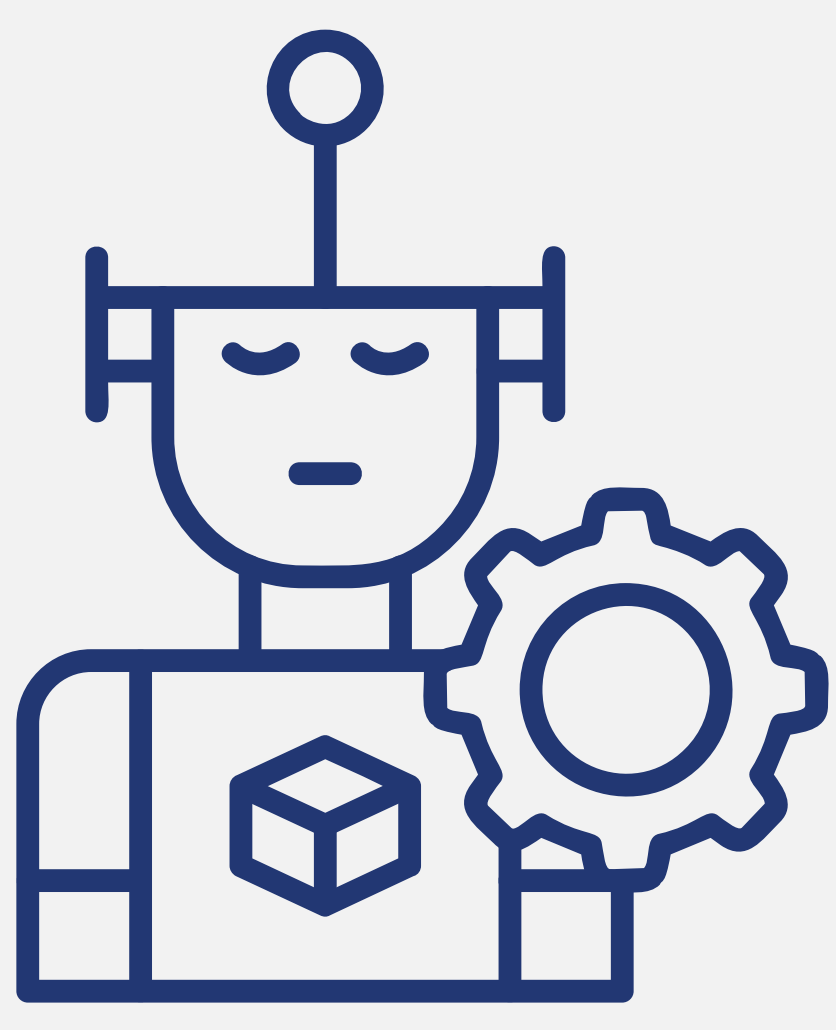
Our Vision is to enable robots to autonomously navigate and perform complex tasks in dynamic environments, pushing the boundaries of what's possible in robotics today.

We will develop robots that are able to:

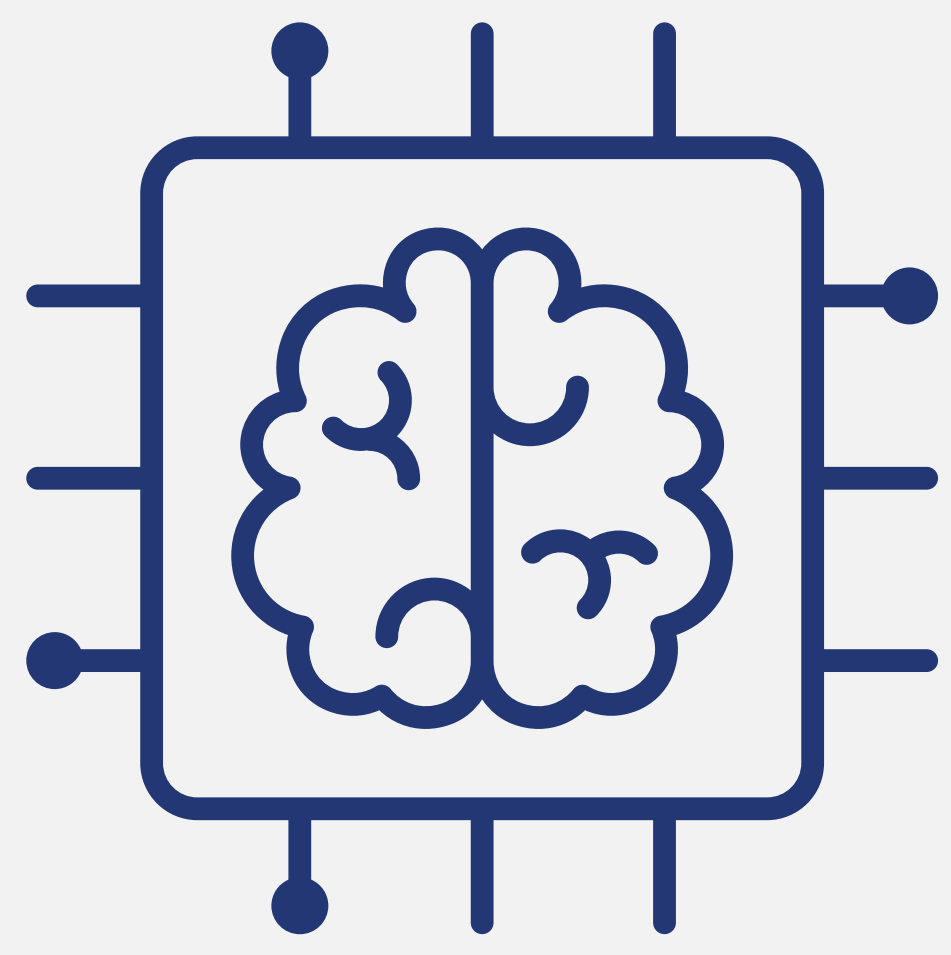
- **understand** their surroundings, including human intentions and needs.
- **expand and improve** the robotic knowledge to perform flexible actions, such as reversing tasks.
- **continuously adapt** robotic knowledge to different domains.



Expected impacts



Increased
robot autonomy



Human-centric
design



Predictive
manufacturing



Training
for human-robot
collaboration



8
Million EU-Funding



12 partners



01 Jan 2024 -
31 Dec 2027



www.inverse-project.org



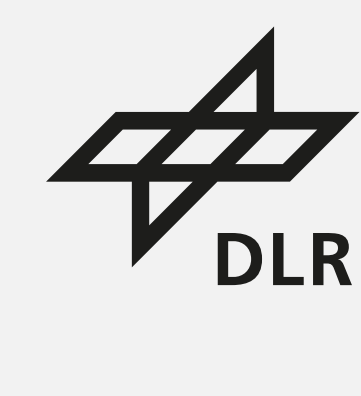
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